

A1 Vector Algebra and Calculus

Prof David Murray

david.murray@eng.ox.ac.uk
www.robots.ox.ac.uk/~dwm/Courses/2VA

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Vector Algebra and Calculus

- 1 Revision of vector algebra, scalar product, vector product
- 2 Triple products, multiple products, applications to geometry
- 3 Differentiation of vector functions, applications to mechanics
- 4 Scalar and vector fields. Line, surface and volume integrals, curvilinear co-ordinates
- 5 Vector operators — grad, div and curl
- 6 Vector Identities, curvilinear co-ordinate systems
- 7 **Gauss' and Stokes' Theorems and extensions**
- 8 Engineering Applications

Gauss' and Stokes' Theorems

This lecture finally begins to deliver on why we introduced div , grad and curl by introducing ...

■ Gauss' Theorem

This enables an integral taken over a volume to be replaced by one taken over the surface bounding that volume, and vice versa.

Why would we want to do that?

Computational efficiency and/or numerical accuracy come to mind.

■ Stokes' Theorem

This enables an integral taken around a closed curve to be replaced by one taken over *any* surface bounded by that curve.

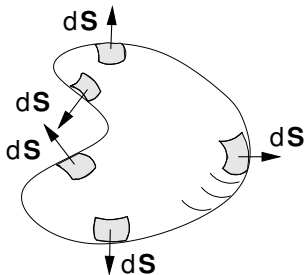
Gauss' Theorem

We want to find the **total outward flux of the vector field $\mathbf{a}(\mathbf{r})$ across the surface S that bounds a volume V :**

$$\int_S \mathbf{a} \cdot d\mathbf{S}$$

$d\mathbf{S}$ is

- 1 normal to the local surface element
- 2 must everywhere point out of the volume



Gauss' Theorem tells us that we can do this by considering the total flux generated inside the volume V :

Gauss' Theorem:

$$\int_S \mathbf{a} \cdot d\mathbf{S} = \int_V \text{div } \mathbf{a} \, dV$$

Informal proof

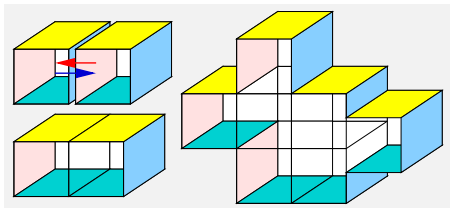
Divergence was *defined* as

$$\operatorname{div} \mathbf{a} \, dV = d(\text{Efflux}) = \sum_{\text{surface of } dV} \mathbf{a} \cdot d\mathbf{S}.$$

If we sum over the volume elements, this results in a sum over the surface elements.

But if two elemental surface touch, their $d\mathbf{S}$ vectors are in opposing direction and cancel.

Thus the sum over surface elements gives the overall **bounding surface**.



$$\int_V \operatorname{div} \mathbf{a} \, dV = \int_{\text{Surface of } V} \mathbf{a} \cdot d\mathbf{S}$$

♣ Example of Gauss' Theorem

Q: Derive $\int_S \mathbf{a} \cdot d\mathbf{S}$ where $\mathbf{a} = z^3 \hat{\mathbf{k}}$ and S is the surface of a sphere of radius R centred on the origin: (i) directly; (ii) by applying Gauss' Theorem.

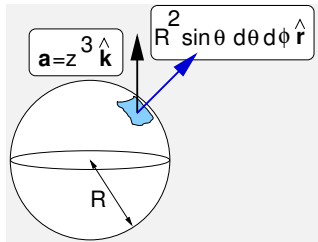
A(i): On the surface of the sphere

$$\mathbf{a} = R^3 \cos^3 \theta \hat{\mathbf{k}}$$

$$d\mathbf{S} = h_\theta d\theta h_\phi d\phi (\hat{\boldsymbol{\theta}} \times \hat{\boldsymbol{\phi}}) = R^2 \sin \theta d\theta d\phi \hat{\mathbf{r}}$$

$$\mathbf{a} \cdot d\mathbf{S} = R^3 \cos^3 \theta R^2 \sin \theta d\theta d\phi (\hat{\mathbf{r}} \cdot \hat{\mathbf{k}})$$

$$\hat{\mathbf{r}} \cdot \hat{\mathbf{k}} = \cos \theta$$



$$\begin{aligned} \int_S \mathbf{a} \cdot d\mathbf{S} &= \int_{\phi=0}^{2\pi} \int_0^{\pi} R^5 \cos^4 \theta \sin \theta d\theta d\phi \\ &= R^5 \int_{\phi=0}^{2\pi} d\phi \int_{\theta=0}^{\pi} \cos^4 \theta \sin \theta d\theta = \frac{2\pi R^5}{5} [-\cos^5 \theta]_0^{\pi} = \frac{4\pi R^5}{5} \end{aligned}$$

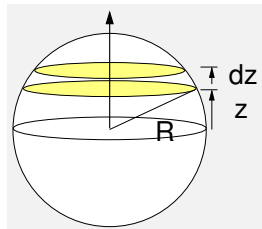
Example /ctd

A(ii): To apply Gauss' Theorem, we need

(i) to work out $\text{div } \mathbf{a}$

$$\mathbf{a} = z^3 \hat{\mathbf{k}}, \quad \Rightarrow \quad \text{div } \mathbf{a} = 3z^2$$

(ii) Perform the volume integral. Because $\text{div } \mathbf{a}$ involves just z , we can divide the sphere into discs of constant z and thickness dz . Then



$$dV = \pi(\text{disc radius})^2 dz = \pi(R^2 - z^2) dz$$

So:

$$\begin{aligned} \int_V \text{div } \mathbf{a} dV &= 3\pi \int_{-R}^R z^2 (R^2 - z^2) dz \\ &= 3\pi \left[\frac{R^2 z^3}{3} - \frac{z^5}{5} \right]_{-R}^R = \frac{4\pi R^5}{5} \end{aligned}$$

Typical! The surface integral is tedious, but volume integral is “straightforward” ...

An Extension to Gauss' Theorem

Suppose vector field is $\mathbf{a} = U(\mathbf{r})\mathbf{c}$ with $U(\mathbf{r})$ a scalar field & \mathbf{c} a **constant** vector. From Lecture 6 result and noting that $\text{div } \mathbf{c} = 0$:

$$\text{div } \mathbf{a} = \text{div } (U\mathbf{c}) = \text{grad } U \cdot \mathbf{c} + U \text{div } \mathbf{c} = \text{grad } U \cdot \mathbf{c}$$

Gauss' Theorem tells us that

$$\int_S U\mathbf{c} \cdot d\mathbf{S} = \int_V \text{grad } U \cdot \mathbf{c} dV$$

But taking constant \mathbf{c} outside ...

$$\mathbf{c} \cdot \left(\int_S U d\mathbf{S} \right) = \mathbf{c} \cdot \left(\int_V \text{grad } U dV \right)$$

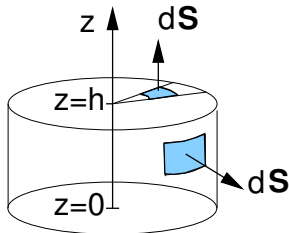
Now \mathbf{c} is arbitrary so result must hold for any vector \mathbf{c} . Hence a ...

Gauss-Theorem extension:

$$\int_S U d\mathbf{S} = \int_V \text{grad } U dV$$

♣ Example

Q: $U = x^2 + y^2 + z^2$ is a scalar field, and volume V is the cylinder $x^2 + y^2 \leq a^2$, $0 \leq z \leq h$. Compute the surface integral $\int_S U d\mathbf{S}$ over the surface of the cylinder.



A1) By direct surface integration ...

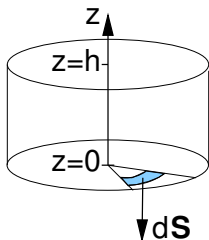
Symmetry gives zero contribution from curved surface, leaving

Top surface:

$$U = (x^2 + y^2 + z^2) = (r^2 + h^2) \quad \text{and} \quad d\mathbf{S} = r dr d\phi \hat{\mathbf{k}}$$

$$\begin{aligned} \Rightarrow \int U d\mathbf{S} &= \int_{r=0}^a (h^2 + r^2) r dr \int_{\phi=0}^{2\pi} d\phi \hat{\mathbf{k}} \\ &= \left[\frac{1}{2} h^2 r^2 + \frac{1}{4} r^4 \right]_0^a 2\pi \hat{\mathbf{k}} = \pi \left(h^2 a^2 + \frac{1}{2} a^4 \right) \hat{\mathbf{k}} \end{aligned}$$

♣ Example /ctd



Bottom surface:

$$U = (x^2 + y^2 + z^2) = (x^2 + y^2) = r^2 \quad \& \quad d\mathbf{S} = -rdrd\phi\hat{\mathbf{k}}$$

$$\int U d\mathbf{S} = - \int_{r=0}^a r^3 dr \int_{\phi=0}^{2\pi} d\phi \hat{\mathbf{k}} = -\frac{\pi a^4}{2} \hat{\mathbf{k}}$$

$$\Rightarrow \underline{\text{Total integral is}} \quad \pi[h^2 a^2 + \frac{1}{2} a^4] \hat{\mathbf{k}} - \frac{1}{2} \pi a^4 \hat{\mathbf{k}} = \underline{\pi h^2 a^2 \hat{\mathbf{k}}}$$

Example, ctd: the volume integration

To test the RHS of the extension $\int_S U d\mathbf{S} = \int_V \text{grad } U dV$ we have to compute

$$\int_V \text{grad } U dV$$

$$U = x^2 + y^2 + z^2 \Rightarrow \text{grad } U = 2(x\hat{\mathbf{i}} + y\hat{\mathbf{j}} + z\hat{\mathbf{k}})$$

So the integral is:

$$\begin{aligned} & 2 \int_V (x\hat{\mathbf{i}} + y\hat{\mathbf{j}} + z\hat{\mathbf{k}}) r dr dz d\phi \\ &= 2 \int_{z=0}^h \int_{r=0}^a \int_{\phi=0}^{2\pi} (r \cos \phi \hat{\mathbf{i}} + r \sin \phi \hat{\mathbf{j}} + z\hat{\mathbf{k}}) r dr dz d\phi \\ &= 0\hat{\mathbf{i}} + 0\hat{\mathbf{j}} + 2 \int_{z=0}^h z dz \int_{r=0}^a r dr \int_{\phi=0}^{2\pi} d\phi \hat{\mathbf{k}} = \underline{\underline{\pi a^2 h^2 \hat{\mathbf{k}}}} \end{aligned}$$

NB: $\hat{\mathbf{i}}$ component is $\propto \int_{\phi=0}^{2\pi} \cos \phi d\phi = 0$ and

the $\hat{\mathbf{j}}$ component is $\propto \int_{\phi=0}^{2\pi} \sin \phi d\phi = 0$

Further extension to Gauss' Theorem

Further “extensions” can be devised ...

For example, apply Gauss' theorem to

$$\mathbf{a}(\mathbf{r}) = \mathbf{b}(\mathbf{r}) \times \mathbf{c}$$

where \mathbf{c} is a constant vector ...

... and see what happens.

Stokes' Theorem

Stokes' Theorem relates a line integral around a closed path ...

... to a surface integral over what is called a *capping surface* of the path.

Stokes' Theorem:

$$\oint_C \mathbf{a} \cdot d\mathbf{r} = \int_S \text{curl } \mathbf{a} \cdot d\mathbf{S}$$

where S is *any* surface capping the curve C .

Note, RHS is $\int (\text{curl } \mathbf{a}) \cdot d\mathbf{S}$.

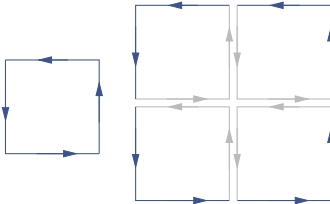
Why couldn't it be $\int \text{curl}(\mathbf{a} \cdot d\mathbf{S})$?

Informal proof

Lecture 5 defined curl as the circulation per unit area, and showed that

$$\sum_{\text{around elemental loop}} \mathbf{a} \cdot d\mathbf{r} = dC = (\nabla \times \mathbf{a}) \cdot d\mathbf{S} .$$

If we add these little loops together, the internal line sections cancel out because the $d\mathbf{r}$'s are in opposite direction but the field \mathbf{a} is not. This gives the larger surface and the larger bounding contour.



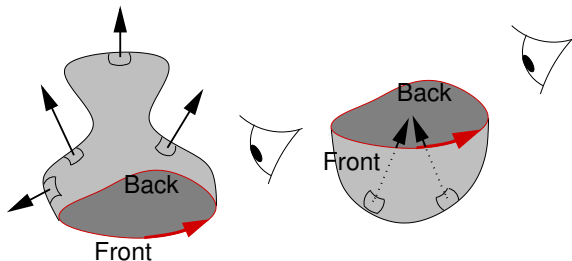
In these diagrams the contour appears planar. In general the contour is any non-intersecting space curve.

Capping Surface

The previous argument says that for a given contour, the capping surface can be **ANY** surface bound by the contour.

Only requirement:

the surface element vectors point in the “general direction” of a r-h screw w.r.t. to the sense of the contour integral.



In practice, (in exam questions?!) the bounding contour is often planar, and the capping surface either flat, or hemispherical, or cylindrical.

♣ Example of Stokes' Theorem

Q: Field $\mathbf{a} = -y^3\hat{\mathbf{i}} + x^3\hat{\mathbf{j}}$ and C is the circle, radius A , centred at $(0, 0)$.
Derive $\oint_C \mathbf{a} \cdot d\mathbf{r}$ (i) directly and (ii) using Stokes' with a planar surface.

A: Directly

On the circle of radius A

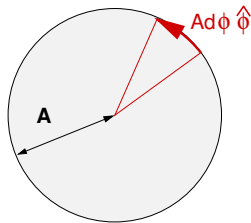
$$\mathbf{a} = A^3(-\sin^3 \phi \hat{\mathbf{i}} + \cos^3 \phi \hat{\mathbf{j}})$$

and

$$d\mathbf{r} = Ad\phi \hat{\boldsymbol{\phi}} = Ad\phi(-\sin \phi \hat{\mathbf{i}} + \cos \phi \hat{\mathbf{j}})$$

so that:

$$\oint_C \mathbf{a} \cdot d\mathbf{r} = \int_0^{2\pi} A^4(\sin^4 \phi + \cos^4 \phi) d\phi = \underline{\underline{\frac{3\pi}{2} A^4}},$$



$$\int_0^{2\pi} \sin^4 \phi d\phi = \int_0^{2\pi} \cos^4 \phi d\phi = \frac{3\pi}{4}$$

Example /ctd

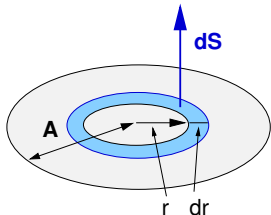
A: (Using Stokes') $\int \text{curl } \mathbf{a} \cdot d\mathbf{S}$ over planar disc ...

$$\text{curl } \mathbf{a} = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -y^3 & x^3 & 0 \end{vmatrix} = 3(x^2 + y^2)\hat{\mathbf{k}} = 3r^2\hat{\mathbf{k}}$$

We choose area elements to be circular strips of radius r thickness dr . Then

$$d\mathbf{S} = r dr d\phi \hat{\mathbf{k}}$$

$$\int_S \text{curl } \mathbf{a} \cdot d\mathbf{S} = 3 \int_{r=0}^A r^3 dr \int_{\phi=0}^{2\pi} d\phi = \frac{3\pi}{2} A^4$$



An Extension to Stokes' Theorem

Try similar “extension” with Stokes ...

Again let $\mathbf{a}(\mathbf{r}) = U(\mathbf{r})\mathbf{c}$, where \mathbf{c} is a constant vector. Then

$$\text{curl } \mathbf{a} = U \text{curl } \mathbf{c} + \text{grad } U \times \mathbf{c}$$

But $\text{curl } \mathbf{c}$ is zero. Stokes' Theorem becomes:

$$\oint_C U(\mathbf{c} \cdot d\mathbf{r}) = \int_S \text{grad } U \times \mathbf{c} \cdot d\mathbf{S} = \int_S \mathbf{c} \cdot (d\mathbf{S} \times \text{grad } U)$$

Re-arranging and taking constant \mathbf{c} out ...

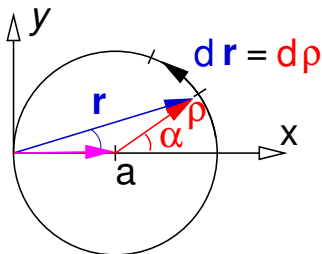
$$\mathbf{c} \cdot \oint_C U d\mathbf{r} = -\mathbf{c} \cdot \int_S \text{grad } U \times d\mathbf{S} .$$

But \mathbf{c} is arbitrary and so

An extension to Stokes': $\oint_C U d\mathbf{r} = -\int_S \text{grad } U \times d\mathbf{S}$

♣ Example of extension to Stokes' Theorem

Q: Derive $\oint_C U d\mathbf{r}$ where $U = x^2 + y^2 + z^2$ and C is the circle $(x - a)^2 + y^2 = a^2, z = 0$, (i) directly and (ii) using Stokes with a planar capping surface.



A(i) Directly: The circle is $\mathbf{r} = a(1 + \cos \alpha)\hat{\mathbf{i}} + a \sin \alpha \hat{\mathbf{j}}$, so

$$U = x^2 + y^2 + z^2 = a^2(1 + \cos \alpha)^2 + a^2 \sin^2 \alpha = 2a^2(1 + \cos \alpha)$$

$$d\mathbf{r} = a d\alpha(-\sin \alpha \hat{\mathbf{i}} + \cos \alpha \hat{\mathbf{j}}) .$$

So,

$$\oint U d\mathbf{r} = 2a^3 \int_{\alpha=0}^{2\pi} (1 + \cos \alpha)(-\sin \alpha \hat{\mathbf{i}} + \cos \alpha \hat{\mathbf{j}}) d\alpha = 2\pi a^3 \hat{\mathbf{j}}$$

(It is worth checking that a zero $\hat{\mathbf{i}}$ component is indeed what you would expect from symmetry.)

Example /ctd

A(ii) Using Stokes'

Using the xy -planar surface

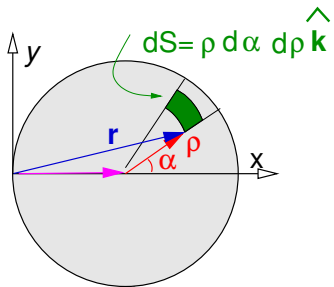
$$\begin{aligned} d\mathbf{S} &= \rho \, d\rho \, d\alpha \, \hat{\mathbf{k}} \\ \text{grad } U &= \text{grad } r^2 = 2\mathbf{r} \\ &= 2(a + \rho \cos \alpha)\hat{\mathbf{i}} + 2\rho \sin \alpha \hat{\mathbf{j}} \end{aligned}$$

so that

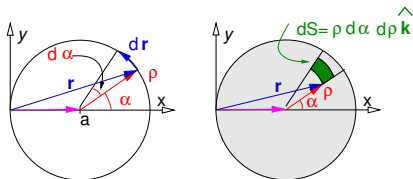
$$\begin{aligned} d\mathbf{S} \times \text{grad } U &= \rho \, d\rho \, d\alpha [2(a + \rho \cos \alpha)(\hat{\mathbf{k}} \times \hat{\mathbf{i}}) + 2\rho \sin \alpha (\hat{\mathbf{k}} \times \hat{\mathbf{j}})] \\ &= \rho \, d\rho \, d\alpha [-2\rho \sin \alpha \hat{\mathbf{i}} + 2(a + \rho \cos \alpha)\hat{\mathbf{j}}] \end{aligned}$$

and as $\int_0^{2\pi} \sin \alpha \, d\alpha = 0$ and $\int_0^{2\pi} \cos \alpha \, d\alpha = 0$

$$\begin{aligned} \int_S d\mathbf{S} \times \text{grad } U &= \int_{\rho=0}^a \int_{\alpha=0}^{2\pi} \rho \, d\rho \, d\alpha (2a\hat{\mathbf{j}}) \\ &= 2\pi \frac{a^2}{2} (2a\hat{\mathbf{j}}) = 2\pi a^3 \hat{\mathbf{j}} \end{aligned}$$



Why were ρ, α used in the last eg?



It is simply a coordinate transformation to decouple the coordinates. In the plane the general position is

$$\mathbf{r} = x\hat{\mathbf{i}} + y\hat{\mathbf{j}} = r \cos \theta \hat{\mathbf{i}} + r \sin \theta \hat{\mathbf{j}} = (a + \rho \cos \alpha)\hat{\mathbf{i}} + \rho \sin \alpha \hat{\mathbf{j}}$$

Going round the circumference, both r and θ change, so

$$d\mathbf{r} = (\cos \theta dr - r \sin \theta d\theta)\hat{\mathbf{i}} + (\sin \theta dr + r \cos \theta d\theta)\hat{\mathbf{j}}$$

whereas because $|\boldsymbol{\rho}| = a$ is constant

$$d\boldsymbol{\rho} = (-a \sin \alpha d\alpha)\hat{\mathbf{i}} + (a \cos \alpha d\alpha)\hat{\mathbf{j}}$$

Summary

In this lecture, we have developed

■ Gauss' Theorem

$$\int_V \operatorname{div} \mathbf{a} \, dV = \int_S \mathbf{a} \cdot d\mathbf{S}$$

If you sum up the $\delta(\text{Effluxes})$ from each $\delta(\text{Volume})$ in an object, you must end up with the overall efflux from the surface.

■ Stokes' Theorem

$$\oint_C \mathbf{a} \cdot d\mathbf{r} = \int_S \operatorname{curl} \mathbf{a} \cdot d\mathbf{S}$$

which says if you add up the $\delta(\text{Circulations})$ per unit area over an open surface, you end up with the Circulation around the rim

- We've seen how to verify and apply the theorems to simple surfaces and volumes using Cartesians, cylindrical and spherical polars.