

1. Let \mathbb{A} be a square finite-dimensional matrix (real elements) such that $\mathbb{A}\mathbb{A}^T = \mathbf{1}$. (i) Show that $\mathbb{A}^T\mathbb{A} = \mathbf{1}$ (ii) Does this result hold for infinite dimensional matrices?

2. Let us define a state using a hardness basis $\{|h\rangle, |s\rangle\}$, where

$$\hat{O}_{\text{HARDNESS}}|h\rangle = |h\rangle \quad \text{and} \quad \hat{O}_{\text{HARDNESS}}|s\rangle = -|s\rangle.$$

Suppose that we are in the state

$$|A\rangle = \cos\theta|h\rangle + e^{i\phi}\sin\theta|s\rangle$$

(i) Is this state normalized? Show your work. If not, normalize it. (ii) Find the state $|B\rangle$ that is orthogonal to $|A\rangle$. Make sure $|B\rangle$ is normalized. (iii) Express $|h\rangle$ and $|s\rangle$ in the $\{|A\rangle, |B\rangle\}$ basis. (iv) What are the possible outcomes of a hardness measurement on state $|A\rangle$ and with what probability will each occur? [Hint: Recall that eigenstates of hermitian operators with different eigenvalues are orthogonal to each other.]

3. If the states $\{|1\rangle, |2\rangle, |3\rangle\}$ form an orthonormal basis and if the operator \hat{G} has the properties

$$\hat{G}|1\rangle = 2|1\rangle - 4|2\rangle + 7|3\rangle$$

$$\hat{G}|2\rangle = -2|1\rangle + 3|3\rangle$$

$$\hat{G}|3\rangle = 11|1\rangle + |2\rangle - 6|3\rangle$$

What is the matrix representation of \hat{G} in the $|1\rangle, |2\rangle, |3\rangle$ basis?

4. Given particles in state

$$|\alpha\rangle = \frac{1}{\sqrt{83}}(-3|1\rangle + 5|2\rangle + 7|3\rangle)$$

where $\{|1\rangle, |2\rangle, |3\rangle\}$ form an orthonormal basis, what are the possible experimental results for a measurement of

$$\hat{Y} = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & -6 \end{pmatrix}$$

(written in this basis) and with what probabilities do they occur?

1.(i)

Since

SOLUTIONS

$$\det(AB) = \det(A) \det(B), \det(A) = \det(A^T), \det(I) = 1$$

we have

$$\det(AA^T) = \det(A) \det(A^T) = \det(A^2) = \det(I) = 1$$

Therefore the inverse of A exists and we have $A^T = A^{-1}$ with $A^{-1}A = AA^{-1} = I$.

(ii)

The answer is no. We have a counterexample. Let

$$A = \begin{pmatrix} 0 & 1 & 0 & 0 & 0 & \dots \\ 0 & 0 & 1 & 0 & 0 & \dots \\ 0 & 0 & 0 & 1 & 0 & \dots \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \end{pmatrix}$$

Then the transpose matrix A^T of A is given by

$$A^T = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & \dots \\ 1 & 0 & 0 & 0 & 0 & \dots \\ 0 & 1 & 0 & 0 & 0 & \dots \\ 0 & 0 & 1 & 0 & 0 & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \end{pmatrix}$$

It follows that

$$AA^T = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & \dots \\ 0 & 1 & 0 & 0 & 0 & \dots \\ 0 & 0 & 1 & 0 & 0 & \dots \\ 0 & 0 & 0 & 1 & 0 & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \end{pmatrix} = I$$

and

$$A^T A = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & \dots \\ 0 & 1 & 0 & 0 & 0 & \dots \\ 0 & 0 & 1 & 0 & 0 & \dots \\ 0 & 0 & 0 & 1 & 0 & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \end{pmatrix} \neq I$$

Consequently,

$$AA^T \neq A^T A$$

$$\begin{aligned}
2.(i) \quad \langle A | A \rangle &= (\cos \theta \langle h | + e^{-i\varphi} \sin \theta \langle s |) (\cos \theta |h\rangle + e^{i\varphi} \sin \theta |s\rangle) \\
&= \cos^2 \theta \langle h | h \rangle + e^{i\varphi} \sin \theta \cos \theta \langle h | s \rangle + e^{-i\varphi} \sin \theta \cos \theta \langle s | h \rangle + \sin^2 \theta \langle s | s \rangle \\
&= \cos^2 \theta + \sin^2 \theta = 1
\end{aligned}$$

which says that the vector is normalized.

$$\begin{aligned}
(ii) \quad |B\rangle &= \alpha |h\rangle + \beta |s\rangle \\
\langle A | B \rangle &= (\cos \theta \langle h | + e^{-i\varphi} \sin \theta \langle s |) (\alpha |h\rangle + \beta |s\rangle) = 0 \\
0 &= \alpha \cos \theta + e^{-i\varphi} \beta \sin \theta \Rightarrow \beta = -e^{i\varphi} \alpha \cot \theta \\
\langle B | B \rangle &= (\alpha^* \langle h | + \beta^* \langle s |) (\alpha |h\rangle + \beta |s\rangle) = |\alpha|^2 + |\beta|^2 = 1 \\
|\alpha|^2 + \cot^2 \theta |\alpha|^2 &= 1 \Rightarrow |\alpha|^2 = \frac{1}{1 + \cot^2 \theta} = \sin^2 \theta \\
\alpha &= \sin \theta \quad , \quad \beta = -e^{i\varphi} \cos \theta \\
|B\rangle &= \sin \theta |h\rangle - e^{i\varphi} \cos \theta |s\rangle
\end{aligned}$$

$$\begin{aligned}
(iii) \quad |A\rangle &= \cos \theta |h\rangle + e^{i\varphi} \sin \theta |s\rangle \\
|B\rangle &= \sin \theta |h\rangle - e^{i\varphi} \cos \theta |s\rangle \\
\langle h | A \rangle &= \cos \theta = \langle A | h \rangle \quad , \quad \langle h | B \rangle = \sin \theta = \langle B | h \rangle \\
\langle s | A \rangle &= e^{i\varphi} \sin \theta = \langle A | s \rangle^* \quad , \quad \langle s | B \rangle = -e^{i\varphi} \cos \theta = \langle B | s \rangle^* \\
|h\rangle &= \langle A | h \rangle |A\rangle + \langle B | h \rangle |B\rangle = \cos \theta |A\rangle + \sin \theta |B\rangle \\
|s\rangle &= \langle A | s \rangle |A\rangle + \langle B | s \rangle |B\rangle \\
&= e^{-i\varphi} \sin \theta |A\rangle - e^{-i\varphi} \cos \theta |B\rangle = e^{-i\varphi} (\sin \theta |A\rangle - \cos \theta |B\rangle) \\
|s\rangle &= \sin \theta |A\rangle - \cos \theta |B\rangle
\end{aligned}$$

since overall phase factors are irrelevant.

$$\begin{aligned}
(iv) \quad P(h|A) &= |\langle h | A \rangle|^2 = \cos^2 \theta \\
P(s|A) &= |\langle s | A \rangle|^2 = \sin^2 \theta
\end{aligned}$$

$$\begin{aligned}
3. \quad \langle 1 | \hat{G} | 1 \rangle &= 2 \langle 1 | 1 \rangle - 4 \langle 1 | 2 \rangle + 7 \langle 1 | 3 \rangle = 2 = G_{11} \\
\langle 2 | \hat{G} | 1 \rangle &= 2 \langle 2 | 1 \rangle - 4 \langle 2 | 2 \rangle + 7 \langle 2 | 3 \rangle = -4 = G_{21} \\
\langle 3 | \hat{G} | 1 \rangle &= 2 \langle 3 | 1 \rangle - 4 \langle 3 | 2 \rangle + 7 \langle 3 | 3 \rangle = 7 = G_{31} \\
\langle 1 | \hat{G} | 2 \rangle &= -2 \langle 1 | 1 \rangle + 3 \langle 1 | 3 \rangle = -2 = G_{12} \\
\langle 2 | \hat{G} | 2 \rangle &= -2 \langle 2 | 1 \rangle + 3 \langle 2 | 3 \rangle = 0 = G_{22} \\
\langle 3 | \hat{G} | 2 \rangle &= -2 \langle 3 | 1 \rangle + 3 \langle 3 | 3 \rangle = 3 = G_{32} \\
\langle 1 | \hat{G} | 3 \rangle &= 11 \langle 1 | 1 \rangle + 2 \langle 1 | 2 \rangle - 6 \langle 1 | 3 \rangle = 11 = G_{13} \\
\langle 2 | \hat{G} | 3 \rangle &= 11 \langle 2 | 1 \rangle + 2 \langle 2 | 2 \rangle - 6 \langle 2 | 3 \rangle = 2 = G_{23} \\
\langle 3 | \hat{G} | 3 \rangle &= 11 \langle 3 | 1 \rangle + 2 \langle 3 | 2 \rangle - 6 \langle 3 | 3 \rangle = -6 = G_{33}
\end{aligned}$$

$$G = \begin{pmatrix} 2 & -2 & 11 \\ -4 & 0 & 2 \\ 7 & 3 & -6 \end{pmatrix}$$

4. We have

$$|\alpha\rangle = \frac{1}{\sqrt{83}} (-3|1\rangle + 5|2\rangle + 7|3\rangle)$$

where the $\{|1\rangle, |2\rangle, |3\rangle\}$ basis is the set of vectors

$$|1\rangle = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \quad |2\rangle = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \quad |3\rangle = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

The observable

$$\hat{Y} = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & -6 \end{pmatrix}$$

has eigenvectors $\{|1\rangle, |2\rangle, |3\rangle\}$ and eigenvalues $2, 3, -6$. The possible values of any measurement are the eigenvalues and the probabilities are given by

$$\begin{aligned} P(2|\alpha) &= |\langle 1 | \alpha \rangle|^2 = \frac{1}{83} |-3 \langle 1 | 1 \rangle + 5 \langle 1 | 2 \rangle + 7 \langle 1 | 3 \rangle|^2 = \frac{9}{83} \\ P(3|\alpha) &= |\langle 2 | \alpha \rangle|^2 = \frac{1}{83} |-3 \langle 2 | 1 \rangle + 5 \langle 2 | 2 \rangle + 7 \langle 2 | 3 \rangle|^2 = \frac{25}{83} \\ P(-6|\alpha) &= |\langle 3 | \alpha \rangle|^2 = \frac{1}{83} |-3 \langle 3 | 1 \rangle + 5 \langle 3 | 2 \rangle + 7 \langle 3 | 3 \rangle|^2 = \frac{49}{83} \end{aligned}$$