

1. A dart of mass 1 kg is dropped from a height of 1 m, with the intention to hit a certain point on the ground. Estimate the limitation set by the uncertainty principle of the accuracy that can be achieved. For simplicity, consider only motion in the  $xy$  plane ( $y$  vertical and  $x$  horizontal).

2. Using the uncertainty principle estimate how long a time a pencil can be balanced on its point.

3. The operator  $A^\dagger$  is called the *hermitian conjugate* (or adjoint) of  $\hat{A}$  if

$$\int_{-\infty}^{+\infty} (\hat{A}^\dagger \phi)^* \psi dx = \int_{-\infty}^{+\infty} \phi^* \hat{A} \psi dx; \quad (1)$$

in bra-ket notation (1) becomes  $\langle A^\dagger \phi | \psi \rangle = \langle \phi | A \psi \rangle$ . Its easy to show that  $(c\hat{A})^\dagger = c^* \hat{A}^\dagger$  and  $(\hat{A} + \hat{B})^\dagger = \hat{A}^\dagger + \hat{B}^\dagger$  just from the properties of the dot product. Using (1) show that  $(\hat{A}^\dagger)^\dagger = \hat{A}$  and  $(\hat{A}\hat{B})^\dagger = \hat{B}^\dagger \hat{A}^\dagger$ .

4. The operator  $\hat{A}$  is called hermitian if  $\hat{A}^\dagger = \hat{A}$ , i.e.

$$\int_{-\infty}^{+\infty} (\hat{A}\phi)^* \psi dx = \int_{-\infty}^{+\infty} \phi^* \hat{A}\psi dx; \quad (2)$$

in bra-ket notation (2) becomes  $\langle A\phi | \psi \rangle = \langle \phi | A\psi \rangle$ . Convince yourself that  $\hat{x}$  and  $\hat{p} = -i\hbar\partial/\partial x$  are hermitian operators.

5. A physical variable must have real expectation values (and eigenvalues). By computing the complex conjugate of the expectation value of a physical variable show that every operator corresponding to an observable is hermitian.

## SOLUTIONS

1. If there was no uncertainty principle, then a dart released from a height  $h$  above the point  $x = 0$  would strike the point  $x = 0$  since we can set both  $x(0) = 0$  and  $v_x(0) = 0$  initially. Quantum mechanics does not let us do this, however. Assume that  $y(0) = h = 1$  m and  $v_y(0) = 0$  for the vertical motion. Any uncertainty principle effects will be negligible in the vertical direction. We also assume that  $x(0) = \Delta x$  and  $v_x(0) = p_x(0)/m = p_x(0) = \Delta p$ , where  $\Delta x \Delta p \approx \hbar$ . We then have the following equations of motion:

$$\begin{cases} y(t) = y(0) + v_y(0)t - \frac{1}{2}gt^2 = h - \frac{1}{2}gt^2 \\ x(t) = x(0) + v_x(0)t = \Delta x + \Delta p t \Rightarrow t = \frac{x - \Delta x}{\Delta p} \end{cases} .$$

We then have

$$y = h - \frac{1}{2}g \left( \frac{x - \Delta x}{\Delta p} \right)^2 .$$

We are interested in finding the minimum value of  $x$  when  $y = 0$  (hits the ground). Substituting  $y = 0$ ,  $h = 1$  m,  $g = 10$  m/s<sup>2</sup>,  $\Delta p = \hbar/\Delta x$  and solving for  $x$  we get

$$x = \Delta x + \frac{0.45\hbar}{\Delta x} .$$

We find the minimum by computing

$$\frac{\partial x}{\partial \Delta x} = 0 = 1 - \frac{0.45\hbar}{(\Delta x)^2} \Rightarrow \Delta x = \sqrt{0.45\hbar} .$$

Therefore, the minimum  $x$  consistent with quantum mechanics is  $x_{\min} = 2\sqrt{0.45\hbar} \approx 10^{-17}$  m. This is a very small distance! An atomic nucleus has a diameter of  $10^{15}$  m.

2. Consider the diagram in Fig. 1. Modeling the pencil as a uniform rod with mass  $m$ , length  $r$ , moment of inertia  $I = \frac{1}{3}mr^2$ , the torque  $\tau$  when it is at an angle  $\theta$  to the vertical is  $\tau = mgr \sin \theta$ . For small deflections,  $\sin \theta \approx \theta$  and we will use that assumption below. Then the equation of motion for the center-of-mass of the pencil becomes

$$I\ddot{\theta} = mgr \sin \theta \Rightarrow \dot{\theta} \frac{d\dot{\theta}}{d\theta} = \frac{mgr}{I} \sin \theta .$$

Integrating we get the conservation equation

$$\frac{\dot{\theta}^2 - \dot{\theta}_0^2}{2} = -\frac{mgr}{I}(\cos \theta - \cos \theta_0) .$$

We then get

$$\frac{d\theta}{dt} = \sqrt{\dot{\theta}_0^2 - \frac{mgr}{I}(\cos \theta - \cos \theta_0)} ,$$

which implies (integrating)

$$t = K_1 \int_{\theta_0}^{\theta_f} \frac{d\theta}{\sqrt{K_2 - \cos \theta}} ,$$

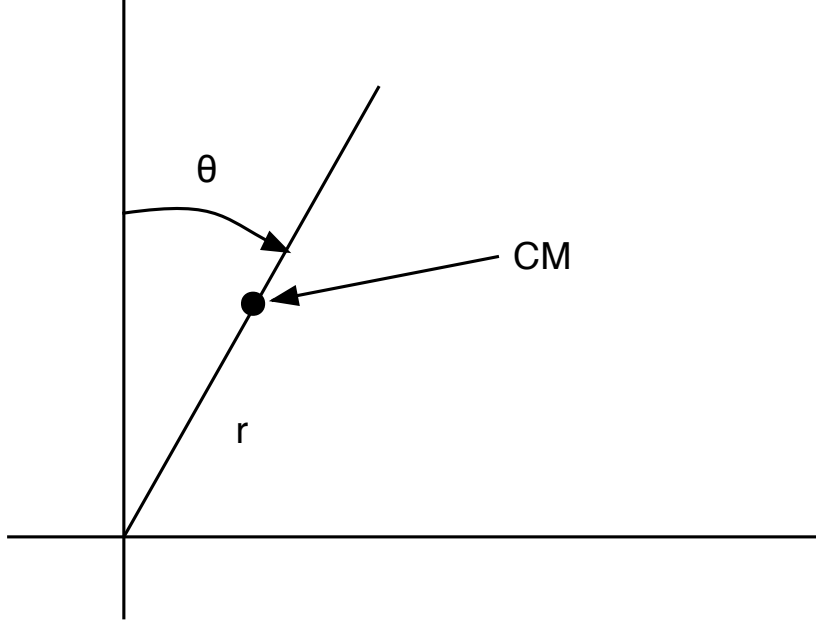


Figure 1: The situation in problem 5.

where

$$K_1 = \sqrt{\frac{I}{2mgr}} \quad \text{and} \quad K_2 = \frac{I\dot{\theta}_0^2 + 2mgr \cos \theta_0}{2mgr}.$$

Now we assume that  $\theta_0 \approx (\Delta\theta)_0$  and  $\dot{\theta}_0 \approx (\Delta\dot{\theta})_0$  which says that the best possible initial conditions are given by the uncertainties. If we are trying to balance the pencil for the longest time, then  $\theta_0$  and  $\dot{\theta}_0$  must be as small as possible. Therefore we have  $K_2 \approx 1 + \epsilon$ , with  $\epsilon \ll 1$ . Therefore, small  $\theta$ -values will dominate the integral, i.e., the pencil spends most of its time at small  $\theta$ . You can see that this is true by trying an experiment!

Therefore we can write  $\cos \theta \approx 1 - \theta^2/2$  which gives

$$t = K_1 \int_{\theta_0}^{\theta_f} \frac{d\theta}{\sqrt{K_3 + \theta^2/2}},$$

where  $K_3 = K_2 - 1 = \epsilon$ . Now let

$$\theta = \sqrt{2K_3} \tan \phi \rightarrow d\theta = \sqrt{2K_3} \sec^2 \phi.$$

We then have

$$t = K_1 \int_{\phi_0}^{\phi_f} \sec \phi \, d\phi,$$

where  $\phi_0 = \tan^{-1}(\theta_0/\sqrt{2K_3})$  and  $\phi_f = \tan^{-1}(\theta_f/\sqrt{2K_3})$ . Now,  $\int \sec \phi \, d\phi = \ln(\sec \phi + \tan \phi)$  and so we get

$$t = \sqrt{2}K_1 \ln \frac{\sec \phi_f + \tan \phi_f}{\sec \phi_0 + \tan \phi_0}.$$

The uncertainty principle says (at best) that initially

$$(\Delta x)_0 (\Delta p_x)_0 = \hbar \Rightarrow [r(\Delta\theta)_0][mr(\Delta\dot{\theta})_0] = \hbar = mr^2\theta_0\dot{\theta}_0,$$

which implies that

$$\dot{\theta}_0 = \frac{\hbar}{mr^2\theta_0}.$$

Thus,

$$K_2 \approx 1 + \frac{\theta_0^2}{2} + \alpha \frac{\hbar^2}{\theta_0^2}$$

where for a typical pencil

$$\alpha = \frac{I}{2m^3gr^5} \approx 0.005.$$

Therefore,

$$K_3 = \epsilon = \frac{\theta_0^2}{2} + \alpha \frac{\hbar^2}{\theta_0^2}$$

and

$$\phi_0 = \tan^{-1} \frac{\theta_0}{\sqrt{2K_3}} \Rightarrow \tan \phi_0 \approx 1 \approx \sec \phi_0.$$

Using  $\theta_f = \pi/2$  (pencil on the floor), we have

$$\frac{\theta_f}{\sqrt{2K_3}} \gg 1 \Rightarrow \sec \phi_f \approx \tan \phi_f \approx \frac{\pi}{2\sqrt{2K_3}}.$$

Therefore,

$$t \approx \sqrt{2}K_1 \ln \frac{\pi}{2\sqrt{2K_3}}$$

where for a typical pencil

$$K_1 = \sqrt{\frac{I}{2mgr}} \approx 0.1.$$

Now, if we want maximum time (upright) we need to minimize  $K_3$ . Thus we have

$$\frac{\partial K_3}{\partial \theta_0} = \theta_0 - \frac{2\alpha\hbar^2}{\theta_0^3} = 0,$$

and we get

$$\theta_0 \approx (2\alpha)^{1/4}\sqrt{\hbar} \approx \frac{1}{3}\sqrt{\hbar} \Rightarrow K_3 \approx \frac{\hbar}{4}.$$

Finally, we have

$$t_{\max} \approx \frac{\sqrt{2}}{2} \frac{1}{10} (-\ln K_3) \approx 0.1(-\ln \hbar) \approx 0.1 \times 34 \sim 3 \text{ to } 4 \text{ s.}$$

Again, try a few experiments!

**3.** (i) From the identity (1) it follows that:

$$\langle (A^\dagger)^\dagger \phi | \psi \rangle = \langle \phi | A^\dagger \psi \rangle = \langle A^\dagger \psi | \phi \rangle^* = \langle \psi | \hat{A} \phi \rangle^* = (\langle A \phi | \psi \rangle^*)^* = \langle \hat{A} \phi | \psi \rangle \Rightarrow (\hat{A}^\dagger)^\dagger = \hat{A} \quad (3)$$

and

$$\langle \phi | \hat{A} \hat{B} \psi \rangle = \langle \hat{A}^\dagger \phi | B \psi \rangle = \langle \hat{B}^\dagger \hat{A}^\dagger \phi | \psi \rangle \Rightarrow (AB)^\dagger = B^\dagger A^\dagger. \quad (4)$$

4. (i) The operator  $\hat{x}$  is hermitian because

$$\int_{-\infty}^{+\infty} (\hat{x}\phi)^* \psi dx = \int_{-\infty}^{+\infty} (x\phi(x))^* \psi(x) dx = \int_{-\infty}^{+\infty} \phi^* x \psi dx = \int_{-\infty}^{+\infty} \psi^* \hat{x}\psi dx. \quad (5)$$

(ii) The operator  $\hat{p}$  is hermitian because

$$\int (\hat{p}\phi)^* \psi dx = \int_{-\infty}^{+\infty} \left(-i\hbar \frac{\partial\phi}{\partial x}\right)^* \psi dx = i\hbar \int_{-\infty}^{+\infty} \left(\frac{\partial\phi}{\partial x}\right)^* \psi dx \quad (6)$$

and after integration by parts, recognizing that the wave function tends to zero as  $x \rightarrow \infty$ , the right-hand side of (6) becomes

$$-i\hbar \int_{-\infty}^{+\infty} \phi^* \frac{\partial\psi}{\partial x} dx = \int_{-\infty}^{+\infty} \phi^* \hat{p}\psi dx. \quad (7)$$

5. We may assert without proof that the expectation value of a physical observable is real, i.e.  $\langle\psi|\hat{A}\psi\rangle = \langle\psi|\hat{A}\psi\rangle^*$ . Now,

$$\langle\psi|\hat{A}\psi\rangle^* = \left[\int_{-\infty}^{+\infty} \psi^*(x)\hat{A}\psi(x)dx\right]^* = \int_{-\infty}^{+\infty} \psi(x)[\hat{A}\psi(x)]^*dx = \int_{-\infty}^{+\infty} [\hat{A}\psi(x)]^*\psi dx = \langle\hat{A}\psi|\psi\rangle, \quad (8)$$

so from (2) it follows that physical observables are represented by hermitian operators.