

PHYSICS 169

Kitt Peak National Observatory

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Tuesday, February 4, 20

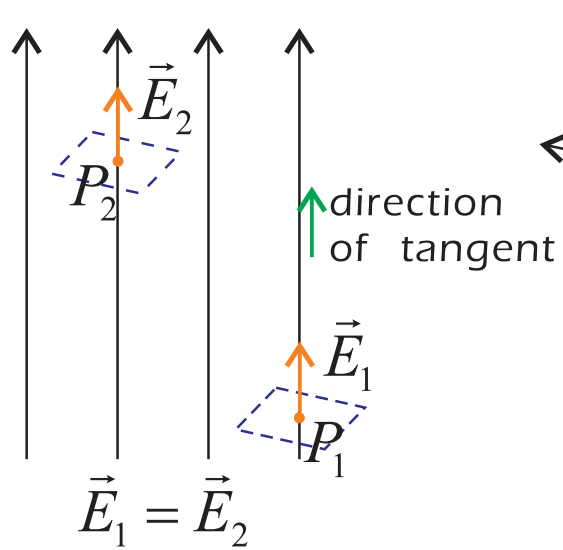
2.1 Electric Field Lines

Recall from last class that  to visualize electric field
we can use a graphical tool called electric field lines

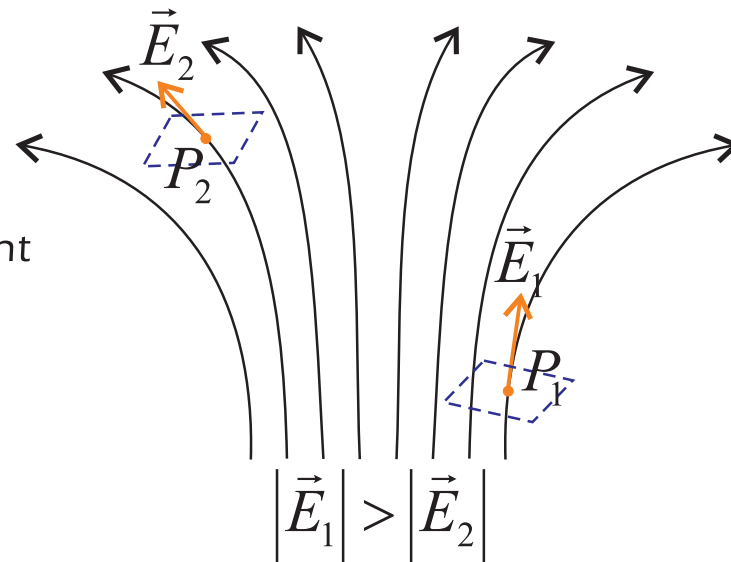
Conventions

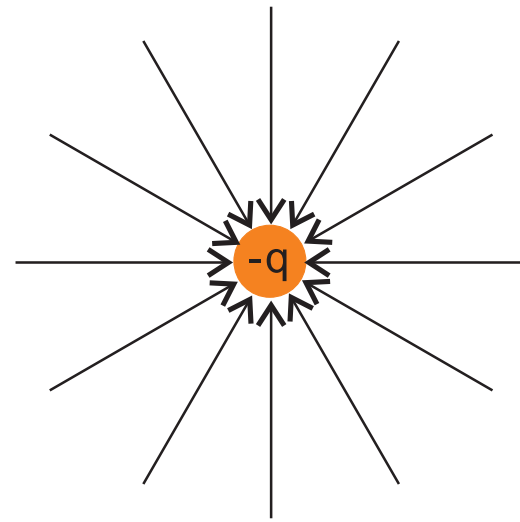
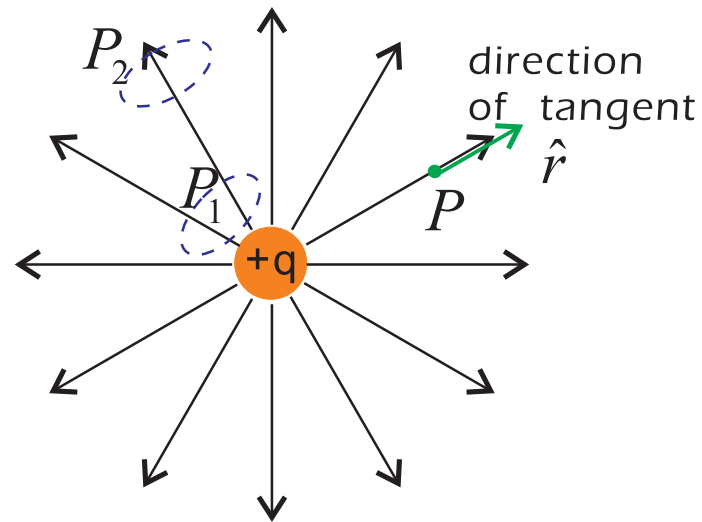
1. Start on positive charges and end on negative charges
2. **Direction** of E-field at any point is given by **tangent** of E-field line
3. **Magnitude** of E-field at any point
proportional to **number of E-field lines per unit area perpendicular to lines**

Uniform E-field



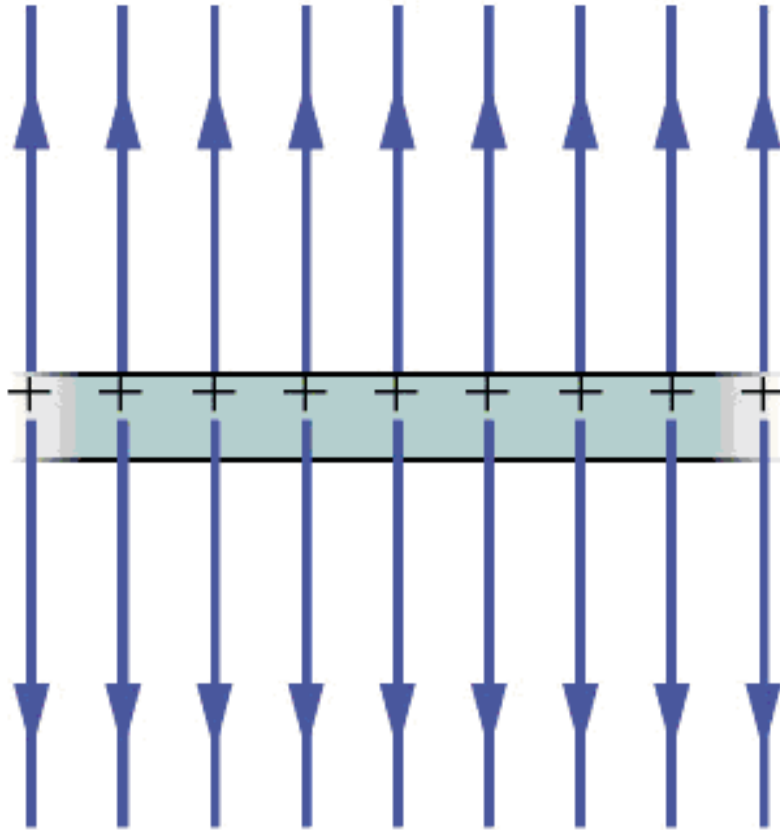
Non-uniform E-field



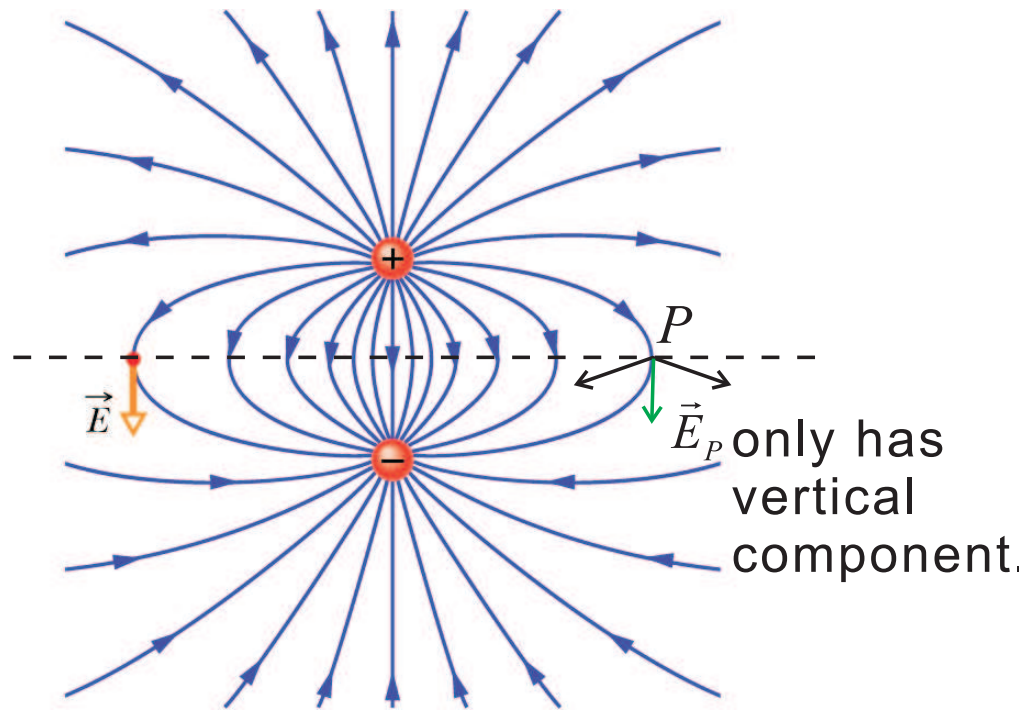


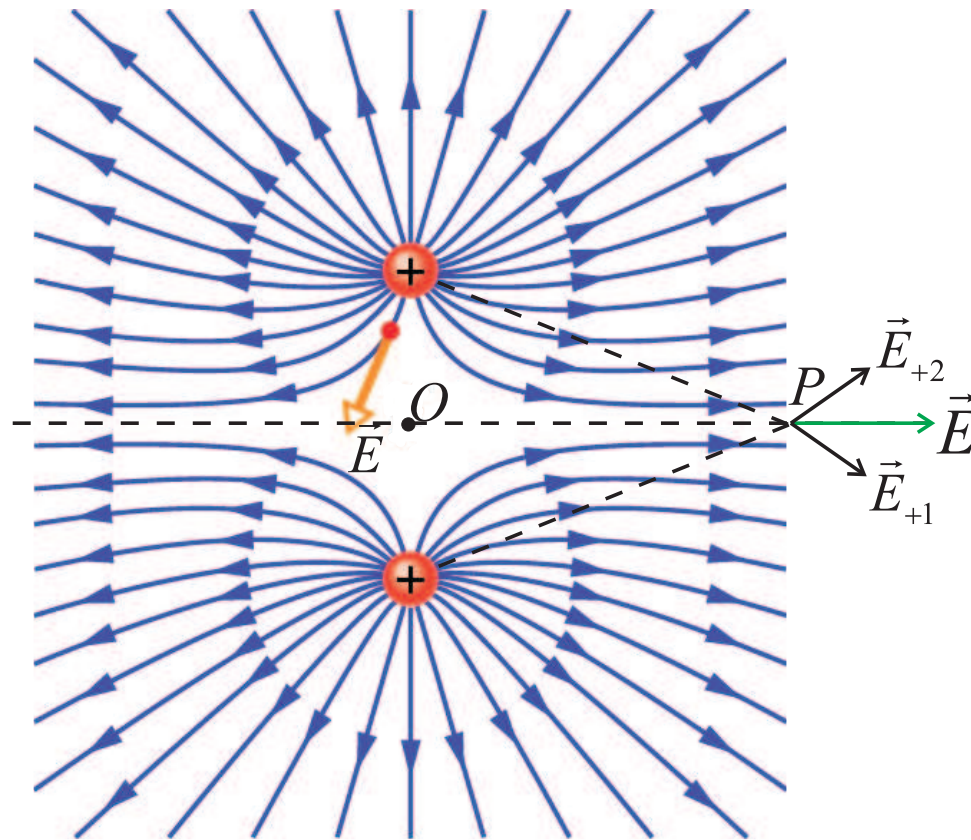
$$|\vec{E}_{P_1}| > |\vec{E}_{P_2}| \quad \vec{E} = \frac{+q}{4\pi\epsilon_0 r^2} \hat{r}$$

Infinite sheet of charge



$$E = \frac{\sigma}{2\epsilon_0}$$





$$\vec{E}_{\text{at point } O} = 0$$

2.2 Dipole in E-field

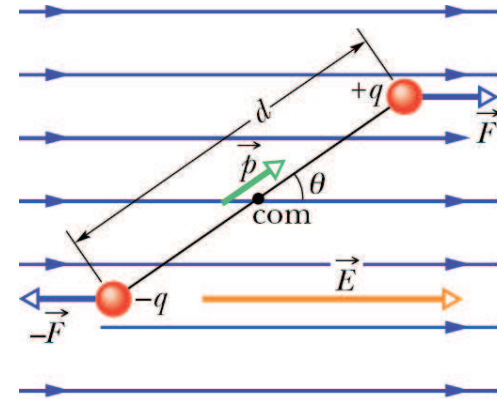
Consider force exerted on dipole in an external E-field

Assumption \rightarrow E-field from dipole doesn't affect external E-field

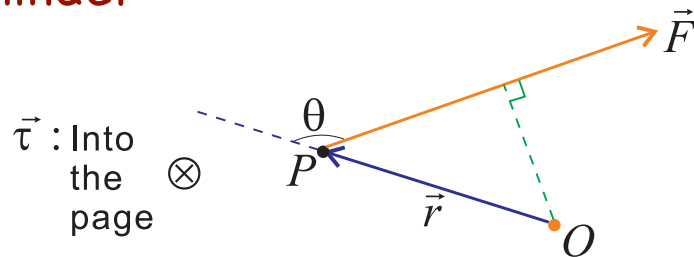
- Dipole moment $\vec{p} = q\vec{d}$
- Force due to E-field on $+q$ and $-q$ charge are **equal and opposite in direction**

Total external force on dipole = 0

BUT \rightarrow There is an external **torque** on center of dipole



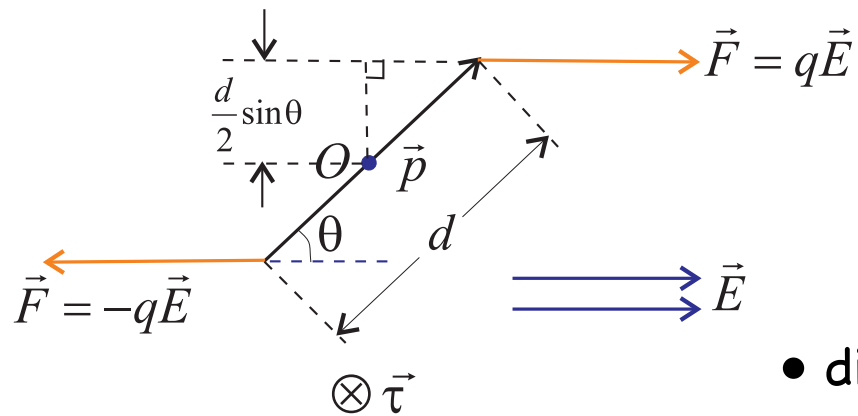
Reminder



Force \vec{F} exerts at point P

force exerts a **torque** $\vec{\tau} = \vec{r} \times \vec{F}$
on point P with respect to point O

Direction of torque vector $\vec{\tau}$ is determined from **right-hand rule**



Net torque $\vec{\tau}$

- direction \rightarrow clockwise torque

- magnitude \rightarrow

$$\tau = \tau_{+q} + \tau_{-q}$$

$$= F \cdot \frac{d}{2} \sin \theta + F \cdot \frac{d}{2} \sin \theta$$

$$= qE \cdot d \sin \theta$$

$$= pE \sin \theta$$

$$\vec{\tau} = \vec{p} \times \vec{E}$$

Energy Consideration

When dipole \vec{p} rotates $d\theta$ \rightarrow E -field does work

Work done by external E -field on dipole

$$dW = -\tau d\theta$$

Negative sign here because torque by E -field acts to **decrease** θ

BUT \rightarrow Because E -field is a **conservative force field**

we can define a **potential energy** (U) for system so that

$$dU = -dW$$

\therefore For dipole in external E -field

$$dU = -dW = pE \sin \theta d\theta$$

$$\begin{aligned} \therefore U(\theta) &= \int dU = \int pE \sin \theta d\theta \\ &= -pE \cos \theta + U_0 \end{aligned}$$

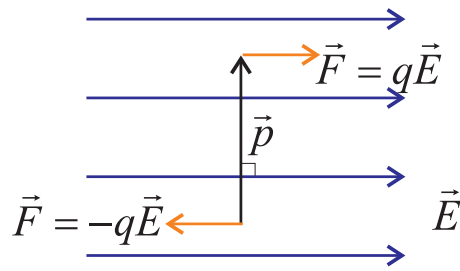
set $U(\theta = 90^\circ) = 0$

$$\therefore 0 = -pE \cos 90^\circ + U_0$$

$$\therefore U_0 = 0$$

\therefore Potential energy

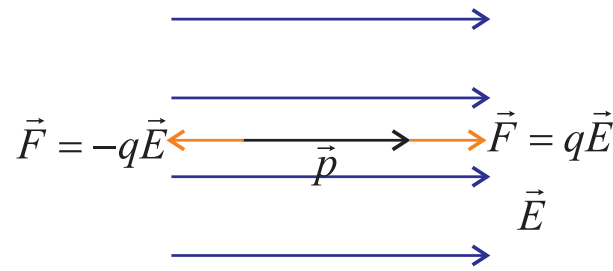
$$U = -pE \cos \theta = -\vec{p} \cdot \vec{E}$$



$$\theta = 90^\circ$$

$$\text{Torque } |\vec{\tau}| = pE$$

$$U = 0 \text{ (define)}$$



$$\theta = 0^\circ$$

$$\text{Torque } |\vec{\tau}| = 0$$

$$U = -pE$$

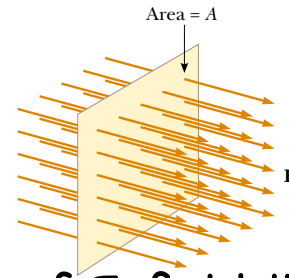
(based on definition)

Minimum energy configuration

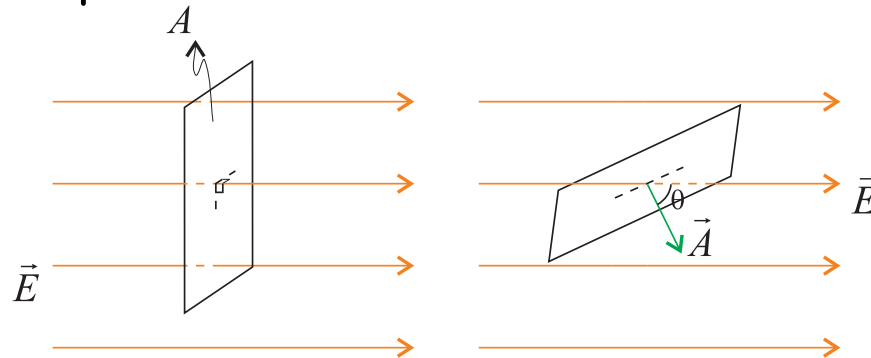
2.3 Electric Flux

Latin \rightarrow flux = "to flow"

Graphically \rightarrow Electric flux Φ_E represents number of E-field lines crossing a surface



Mathematically \rightarrow



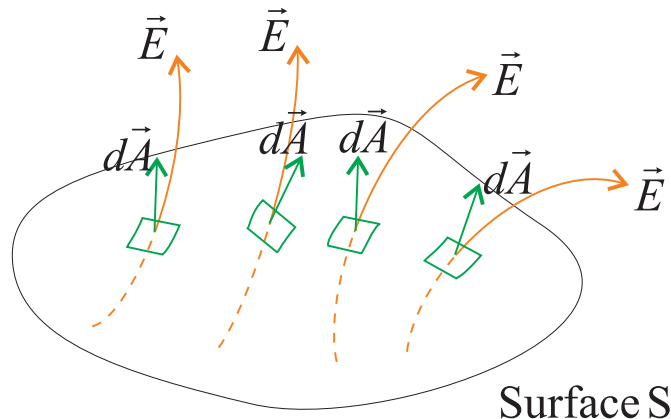
$$\Phi_E = EA$$

$$\Phi_E = \vec{E} \cdot \vec{A}$$

Reminder \rightarrow Vector of area \vec{A} is perpendicular to area A

For non-uniform E-field & surface

direction of area vector \vec{A} is not uniform



$d\vec{A}$ = Area vector for small area element dA

\therefore Electric flux $d\Phi_E = \vec{E} \cdot d\vec{A}$

Electric flux of \vec{E} through surface S $\rightarrow \Phi_E = \int_S \vec{E} \cdot d\vec{A}$

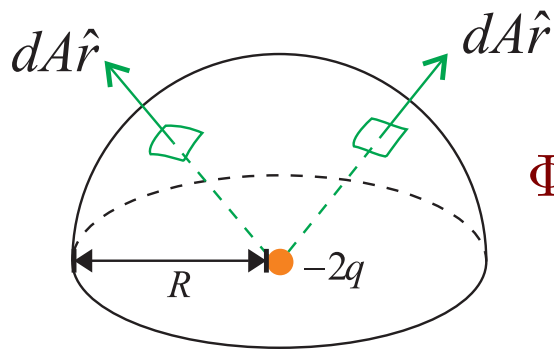
$\int_S =$ Surface integral over surface S

$=$ Integration of integral over all area elements on surface S

Example

$S =$ hemisphere radius R

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \cdot \frac{-2q}{r^2} \hat{r} = \frac{-q}{2\pi\epsilon_0 R^2} \hat{r}$$



For a hemisphere, $d\vec{A} = dA \hat{r}$

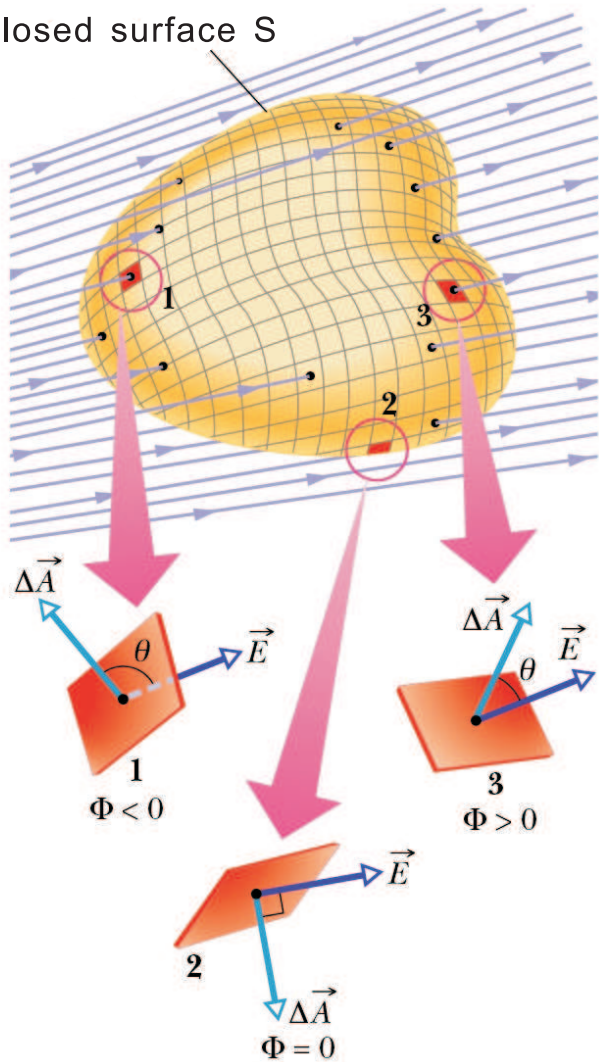
$$\Phi_E = \int_S \frac{-q}{2\pi\epsilon_0 R^2} \hat{r} \cdot (dA \hat{r}) \quad (\because \hat{r} \cdot \hat{r} = 1)$$

$$= -\frac{q}{2\pi\epsilon_0 R^2} \underbrace{\int_S dA}_{2\pi R^2}$$
$$= \frac{-q}{\epsilon_0}$$

$$\int_S dA = \text{Surface area of } S$$

For a closed surface

Closed surface S



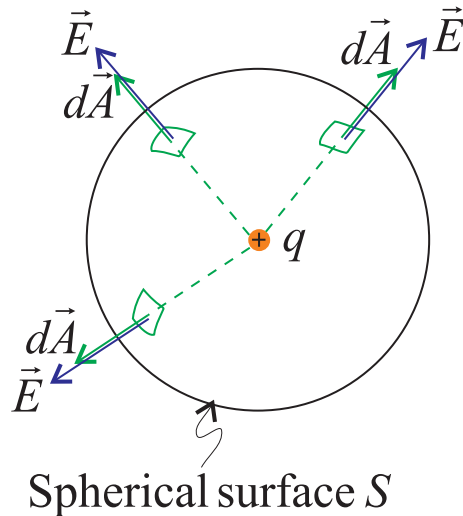
Recall → Direction of area vector $d\vec{A}$ goes **from inside to outside** of closed surface S

Electric flux over closed surface S

$$\Phi_E = \oint_S \vec{E} \cdot d\vec{A}$$

\oint_S = Surface integral over closed surface S

Example



Electric flux of charge q over closed spherical surface of radius R

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \cdot \frac{q}{r^2} \hat{r} = \frac{q}{4\pi\epsilon_0 R^2} \hat{r} \text{ at surface}$$

Again, $d\vec{A} = dA \cdot \hat{r}$

$$\begin{aligned} \therefore \Phi_E &= \oint_S \overbrace{\frac{q}{4\pi\epsilon_0 R^2} \hat{r}}^{\vec{E}} \cdot \overbrace{dA \hat{r}}^{d\vec{A}} \\ &= \frac{q}{4\pi\epsilon_0 R^2} \underbrace{\oint_S dA}_{\text{Total surface area of } S = 4\pi R^2} \end{aligned}$$

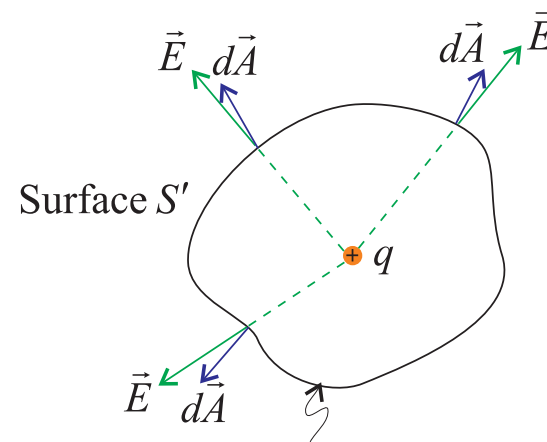
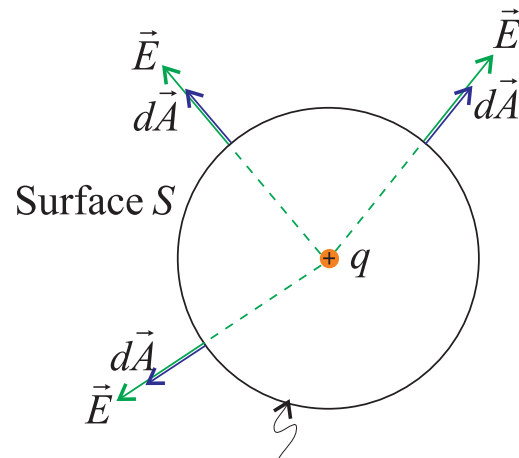
$$\Phi_E = \frac{q}{\epsilon_0}$$

IMPORTANT POINT

If we remove spherical symmetry of closed surface S

total number of E -field lines crossing surface remains same

\therefore electric flux Φ_E



$\vec{E} \parallel d\vec{A} \parallel \vec{r}$ over surface S

\vec{E} is not $\parallel d\vec{A}$ over surface S'

$$\Phi_E = \oint_S \vec{E} \cdot d\vec{A} = \oint_{S'} \vec{E} \cdot d\vec{A} = \frac{q}{\epsilon_0}$$

2.4 Gauss' Law

The net flux through any closed surface is $\Rightarrow \Phi_E = \oint_S \vec{E} \cdot d\vec{A} = \frac{q}{\epsilon_0}$

q represents the net charge inside the surface

\vec{E} represents the electric field at any point on the surface

PROOF

Consider spherical surface of radius r containing area element ΔA

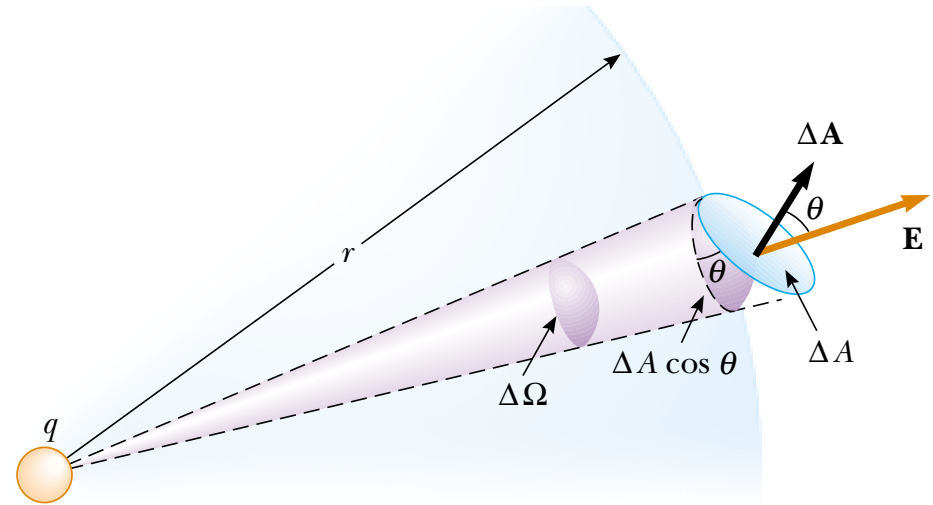
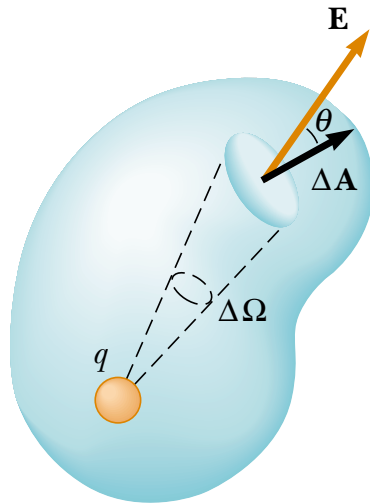
Solid angle subtended at center of the sphere by this element is defined to be

$$\Delta\Omega = \frac{\Delta A}{r^2}$$

Because surface area of sphere is $4\pi r^2$

total solid angle subtended by the sphere is $\Rightarrow \Omega = \frac{4\pi r^2}{r^2} = 4\pi$ steradians

Consider point charge q surrounded by closed surface of arbitrary shape



Total electric flux through this surface can be obtained

by evaluating $\vec{E} \cdot \Delta\vec{A}$ for each small area element ΔA

and summing over all elements

The flux through each element is

$$\Delta\Phi_E = \vec{E} \cdot \Delta\vec{A} = E\Delta A \cos\theta = \frac{q}{4\pi\epsilon_0 r^2} \Delta A \cos\theta$$

r → distance from charge to area element

θ → angle between electric field \vec{E} and $\Delta\vec{A}$ for the element

for point charge $\triangleright E = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2}$

Projection of area element perpendicular to radius vector is $\Delta A \cos \theta$

$\frac{\Delta A \cos \theta}{r^2} \triangleright$ solid angle $\Delta \Omega$ that surface element ΔA subtends at charge q

$\Delta \Omega$ is also solid angle subtended by area element of spherical surface of radius r

Because total solid angle at a point is 4π steradians

total flux through the closed surface is

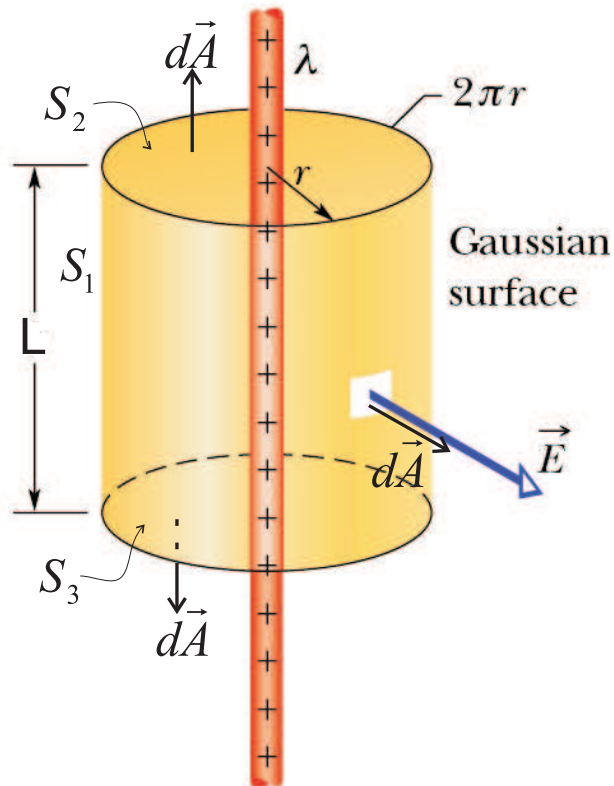


$$\Phi_E = \frac{1}{4\pi\epsilon_0} q \oint \frac{dA \cos \theta}{r^2} = \frac{1}{4\pi\epsilon_0} \oint d\Omega = \frac{q}{\epsilon_0}$$

Note that this result is independent of the shape of the closed surface and independent of the position of the charge within the surface

2.5 E-field Calculation with Gauss' Law

(A) Infinite line of charge



Linear charge density λ

Cylindrical symmetry

E -field directs radially outward from rod

Construct Gaussian surface S

in shape of **cylinder**

making up of a curved surface S_1

and top and bottom circles S_2, S_3

Gauss' Law $\Rightarrow \oint_S \vec{E} \cdot d\vec{A} = \frac{\text{Total charge}}{\epsilon_0} = \frac{\lambda L}{\epsilon_0}$

$$\oint_S \vec{E} \cdot d\vec{A} = \underbrace{\int_{S_1} \vec{E} \cdot d\vec{A}}_{\vec{E} \parallel d\vec{A}} + \underbrace{\int_{S_2} \vec{E} \cdot d\vec{A} + \int_{S_3} \vec{E} \cdot d\vec{A}}_{=0 \because \vec{E} \perp d\vec{A}}$$

$$\therefore E \underbrace{\int_{S_1} dA}_{\text{Total area of surface } S_1} = \frac{\lambda L}{\epsilon_0}$$

Total area of surface S_1

$$E(2\pi r L) = \frac{\lambda L}{\epsilon_0}$$

$$\therefore E = \frac{\lambda}{2\pi\epsilon_0 r}$$

$$\vec{E} = \frac{\lambda}{2\pi\epsilon_0 r} \hat{r}$$

(B) Infinite sheet of charge

Uniform surface charge density σ

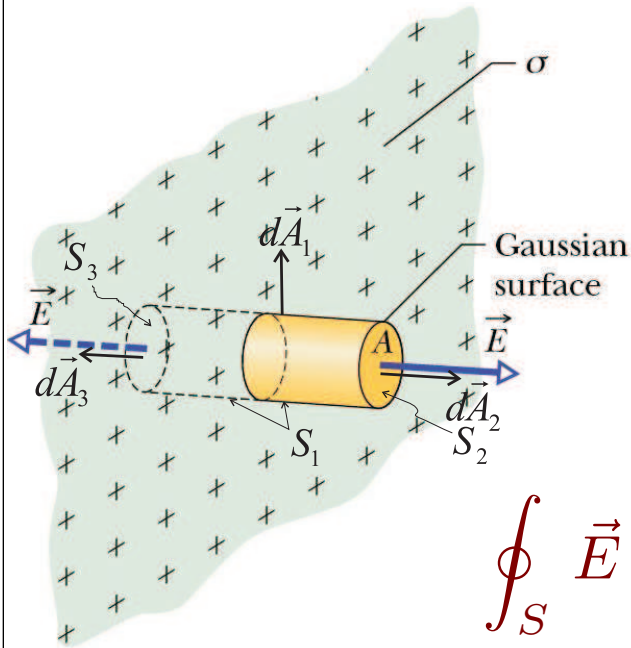
Planar symmetry

E -field directs perpendicular to sheet

Construct a Gaussian surface S

in shape of a **cylinder**

of cross-sectional area A



$$\oint_S \vec{E} \cdot d\vec{A} = \frac{A\sigma}{\epsilon_0}$$

Gauss' Law $\Rightarrow \int_{S_1} \vec{E} \cdot d\vec{A} = 0 \quad \because \vec{E} \perp d\vec{A}$ over whole surface S_1

$$\int_{S_2} \vec{E} \cdot d\vec{A} + \int_{S_3} \vec{E} \cdot d\vec{A} = 2EA \quad (\vec{E} \parallel d\vec{A}_2, \vec{E} \parallel d\vec{A}_3)$$

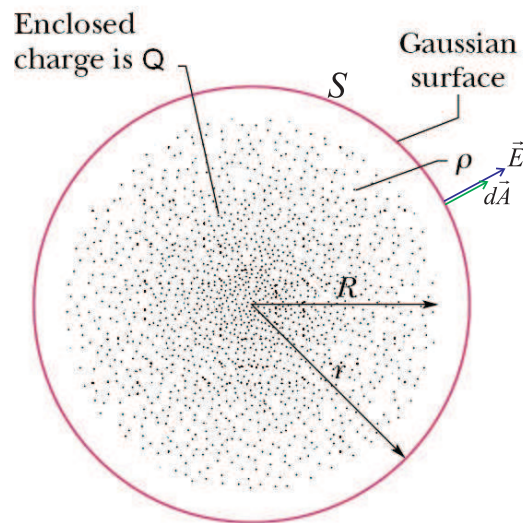
Note \Rightarrow For S_2 both \vec{E} and $d\vec{A}_2$ point right
For S_3 both \vec{E} and $d\vec{A}_3$ point left

$$\therefore 2EA = \frac{A\sigma}{\epsilon_0} \Rightarrow E = \frac{\sigma}{2\epsilon_0}$$

(C) Uniformly charged sphere **Total charge** $\rightarrow Q$
Spherical symmetry

(a) For $r > R$

Consider a spherical Gaussian surface S of radius r



Gauss' Law $\rightarrow \oint_S \vec{E} \cdot d\vec{A} = \frac{Q}{\epsilon_0}$

$\vec{E} \parallel d\vec{A} \parallel \hat{r}$

$\oint_S E \cdot dA = \frac{Q}{\epsilon_0}$

$E \underbrace{\oint_S dA}_{\text{surface area of } S} = \frac{Q}{\epsilon_0}$

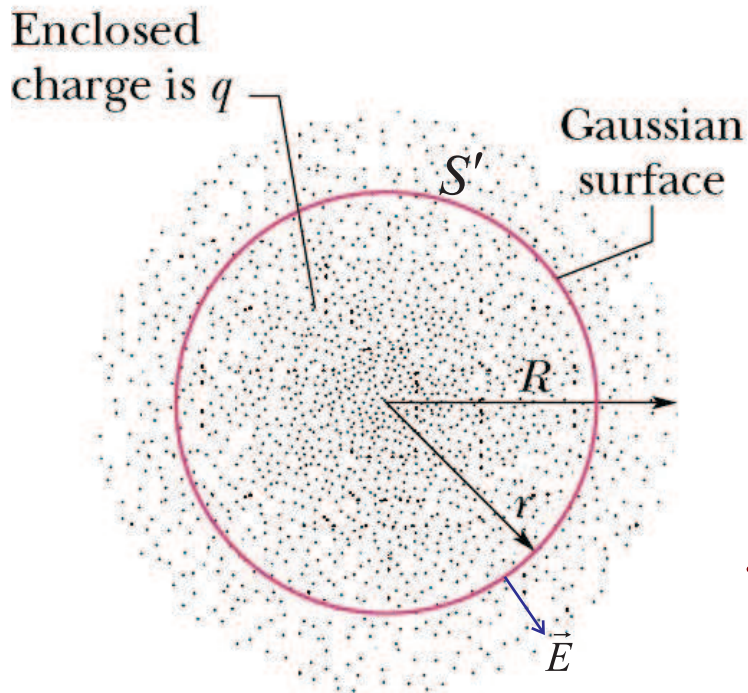
surface area of $S = 4\pi r^2$

$\therefore \vec{E} = \frac{Q}{4\pi\epsilon_0 r^2} \hat{r} \quad \text{for } r > R$

(b) For $r < R$

Consider a spherical Gaussian surface S' of radius $r < R$

total charge included q is **proportional to volume included in S'**



$$\therefore \frac{q}{Q} = \frac{\text{Volume enclosed by } S'}{\text{Total volume of sphere}}$$

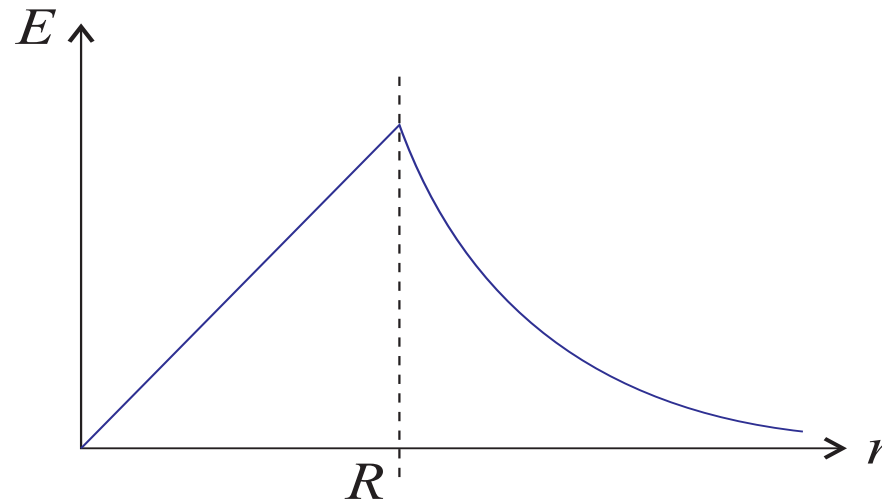
$$\frac{q}{Q} = \frac{4/3\pi r^3}{4/3\pi R^3} \Rightarrow q = \frac{r^3}{R^3} Q$$

Gauss' Law $\Rightarrow \oint_{S'} \vec{E} \cdot d\vec{A} = \frac{q}{\epsilon_0}$

$$E \underbrace{\oint_{S'} dA}_{\text{surface area of } S'} = \frac{r^3}{R^3} \frac{1}{\epsilon_0} \cdot Q$$

surface area of $S' = 4\pi r^2$

$$\therefore \vec{E} = \frac{1}{4\pi\epsilon_0} \cdot \frac{Q}{R^3} r \hat{r} \quad \text{for } r \leq R$$



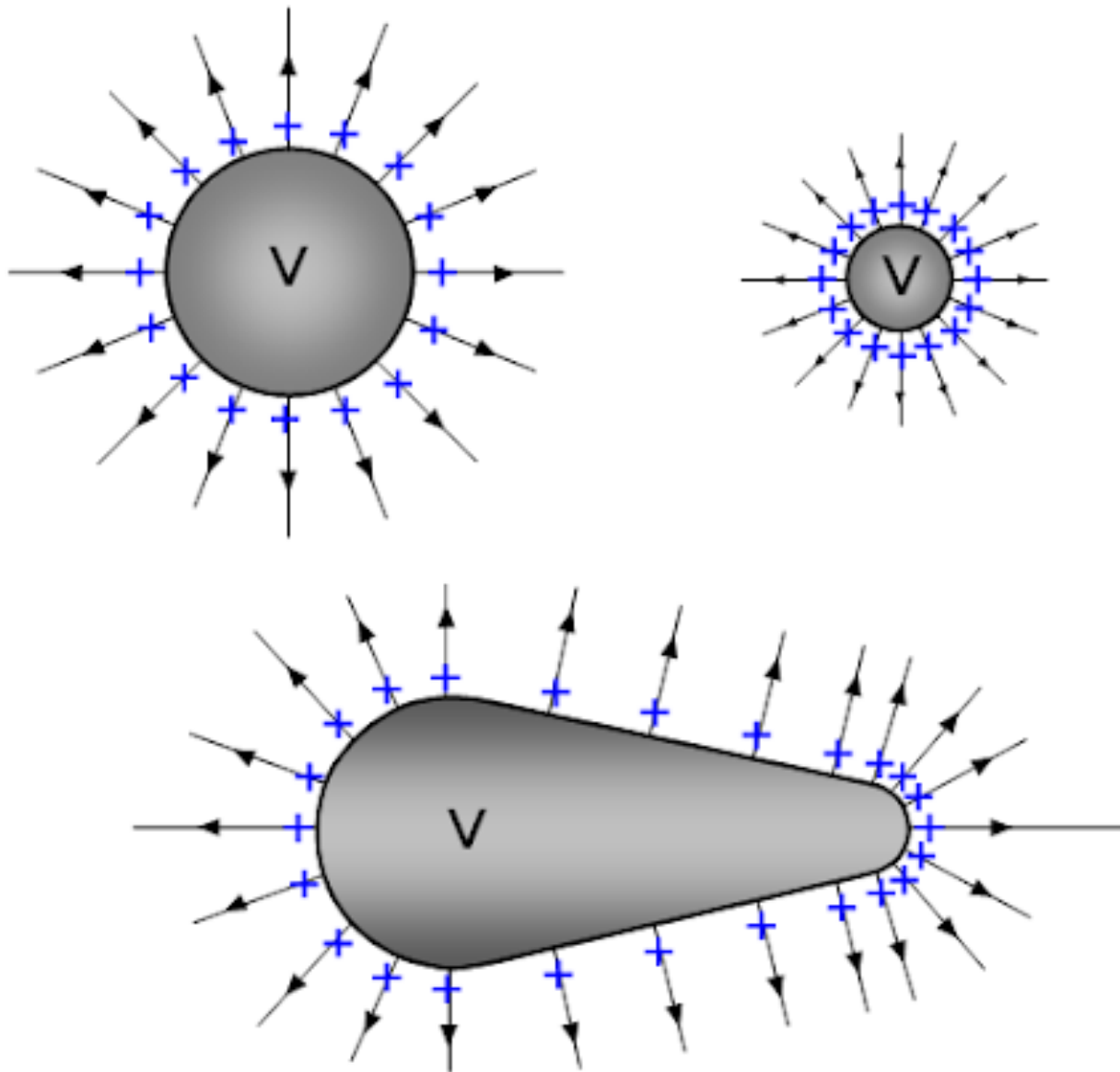
2.6 Conductors in electrostatic equilibrium

Electrical conductors contain charges (electrons) that are not bound to any atom and therefore are free to move about within the material

When there is no net motion of charge within a conductor
the conductor is in electrostatic equilibrium

A conductor in electrostatic equilibrium has the following properties:

1. The electric field is zero everywhere inside the conductor
2. If an isolated conductor carries a charge the charge resides on its surface
3. The electric field just outside a charged conductor is perpendicular to the surface of the conductor and has a magnitude σ/ϵ_0
 σ surface charge density at that point
4. On an irregularly shaped conductor σ surface charge density is greatest at locations where the radius of curvature of the surface is smallest



Consider a Gaussian surface S of shape of cylinder

$$\oint_S \vec{E} \cdot d\vec{A} = \frac{\sigma A}{\epsilon_0}$$

$$\int_{S_1} \vec{E} \cdot d\vec{A} = 0 \quad (\because \vec{E} \perp d\vec{A})$$

$$\int_{S_3} \vec{E} \cdot d\vec{A} = 0 \quad (\because \vec{E} = 0 \text{ inside conductor})$$

$$\int_{S_2} \vec{E} \cdot d\vec{A} = E \underbrace{\int_{S_2} dA}_{\text{Area of } S_2} \quad (\because \vec{E} \parallel d\vec{A}) = EA$$

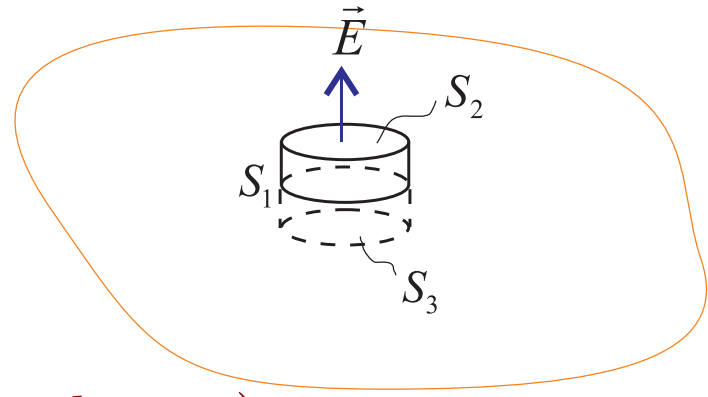
$$\therefore \text{Gauss' Law} \Rightarrow EA = \frac{\sigma A}{\epsilon_0}$$

$$\therefore \text{On conductor surface } E = \frac{\sigma}{\epsilon_0}$$

BUT there is no charge inside conductors

$$\therefore \text{Inside conductors } E = 0 \quad \text{Always!}$$

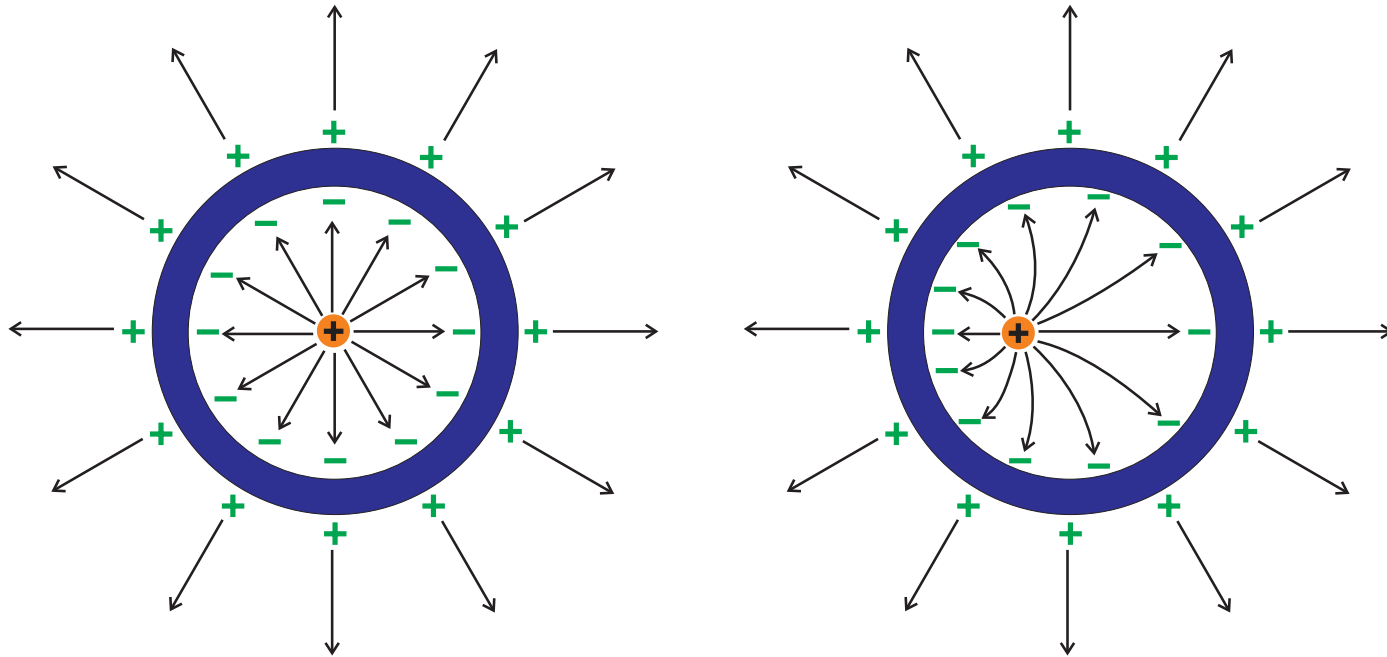
Notice: Surface charge density on a conductor's surface is **not uniform**



Example

Conductor with a charge inside

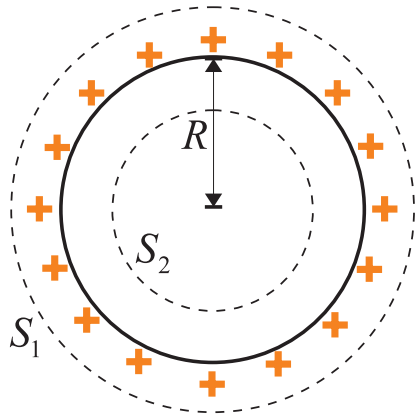
Note \blacktriangleright This is not an isolated system (because of charge inside)



Note \blacktriangleright In **Both** cases $\vec{E} = \frac{1}{4\pi\epsilon_0} \cdot \frac{q}{r^2} \hat{r}$ outside

Example

I. Charge sprayed on a conductor sphere



all charges move to **surface** of conductors

Total charges = Q

(i) For $r < R$ consider Gaussian surface S_2

$$\oint_{S_2} \vec{E} \cdot d\vec{A} = 0 \Rightarrow \vec{E} = 0 \text{ everywhere}$$

Consider Gaussian surface S_1

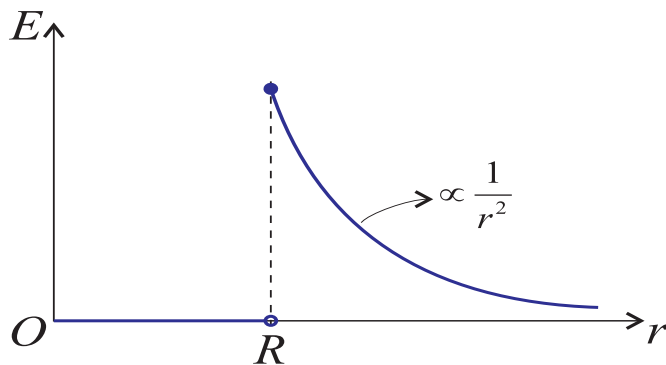
$$\oint_{S_1} \vec{E} \cdot d\vec{A} = \frac{Q}{\epsilon_0}$$

For a conductor

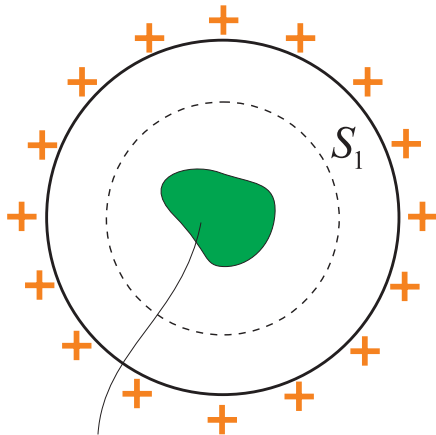
$$E \underbrace{\oint_{S_1} d\vec{A}}_{4\pi r^2} = \frac{Q}{\epsilon_0} \quad (\overbrace{\vec{E} \parallel d\vec{A} \parallel \hat{r}})$$

Spherically symmetric

$$E = \frac{Q}{4\pi\epsilon_0 r^2}$$



II. Conductor sphere with hole inside



Conducting materials removed inside

Consider Gaussian surface S_1

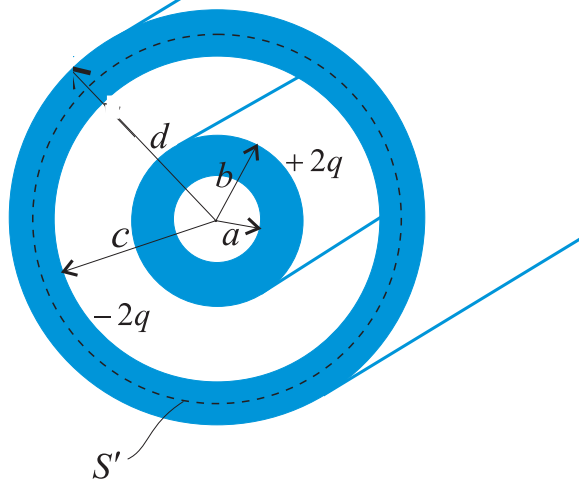
Total charge included = 0

\therefore E-field = 0 inside

E-field is identical to case of a solid conductor!!

III. A long hollow cylindrical conductor

Cross-section



Example

Inside hollow cylinder ($+2q$)

$\left\{ \begin{array}{l} \text{Inner radius } a \\ \text{Outer radius } b \end{array} \right.$

Outside hollow cylinder ($-2q$)

$\left\{ \begin{array}{l} \text{Inner radius } c \\ \text{Outer radius } d \end{array} \right.$

Question

Find charge on each surface of conductor ?

For inside hollow cylinder charges distribute only on surface

\therefore Inner radius a surface \rightarrow charge = 0

Outer radius b surface \rightarrow charge = $+2q$

For outside hollow cylinder

charges do not distribute only on outside surface

\therefore It's not an isolated system **(There are charges inside!)**

Consider Gaussian surface S' inside conductor

E-field always = 0

Need charge $-2q$ on radius c surface to balance charge of inner cylinder

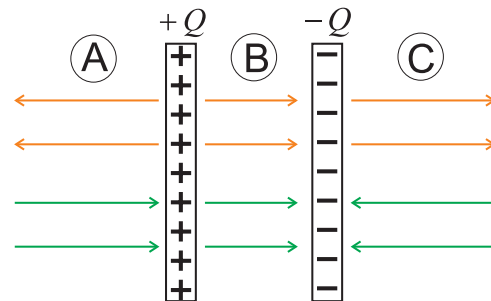
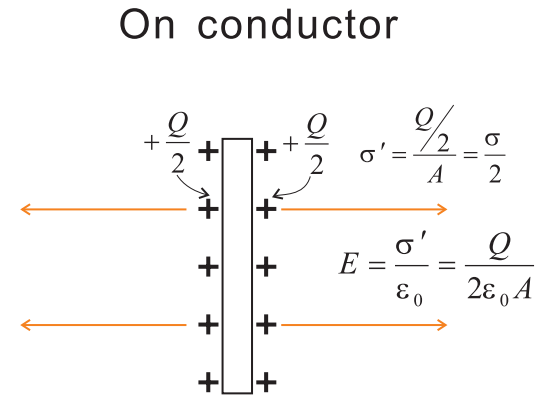
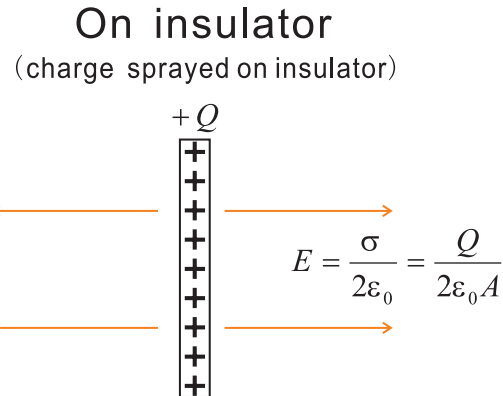
\therefore charge on radius d surface = $-q$

IV. Large sheets of charge

Total charge Q on sheet of area A

Surface charge density $\sigma = \frac{Q}{A}$

By principle of superposition



Region A

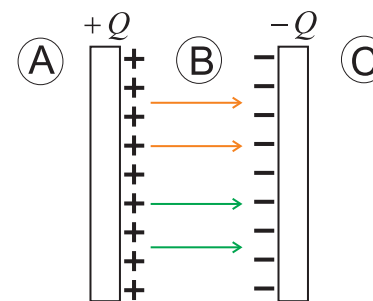
$E = 0$

Region B

$E = \frac{Q}{\epsilon_0 A}$

Region C

$E = 0$



$E = 0$

$E = \frac{Q}{\epsilon_0 A}$

$E = 0$





